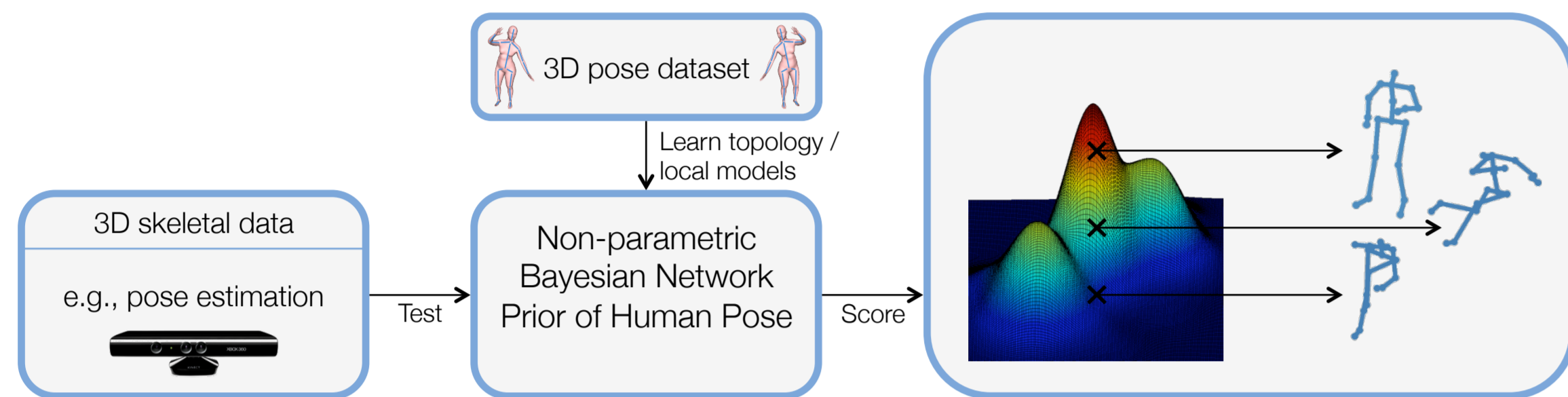




1 Overview

- We propose a general-purpose Bayesian network prior of human pose.



- Fully non-parametric:** Estimation of both optimal information-theoretic topology and local conditional distributions from data.
- Compositional:** Effective handling of the combinatorial explosion of articulated objects, thereby improving generalization.
- Superior performance:** Better data representation than traditional global models and parametric networks on the large Human 3.6M dataset.
- Real-time:** Fast and accurate computation of approximate likelihoods on datasets with up to 100k training poses.

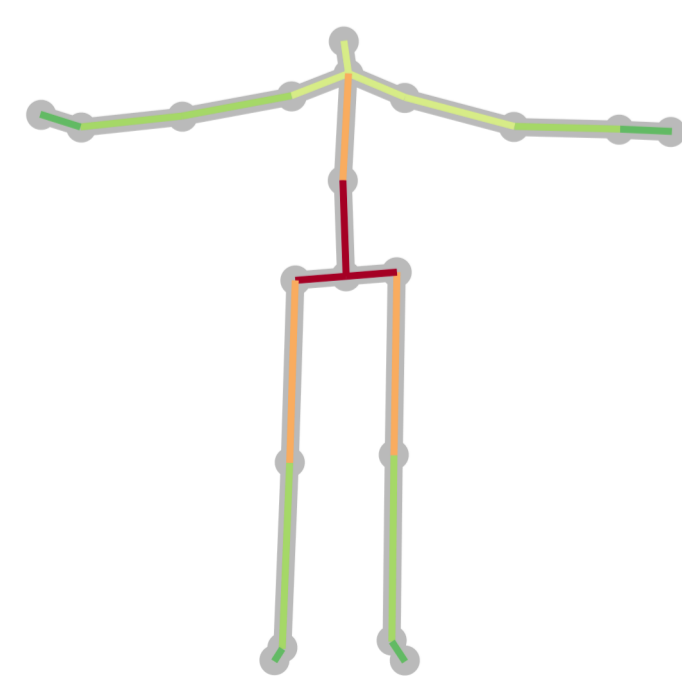
2 Non-parametric Networks

Learn a sparse and non-parametric Bayesian network $B = (p, \mathcal{G}(V, E))$.

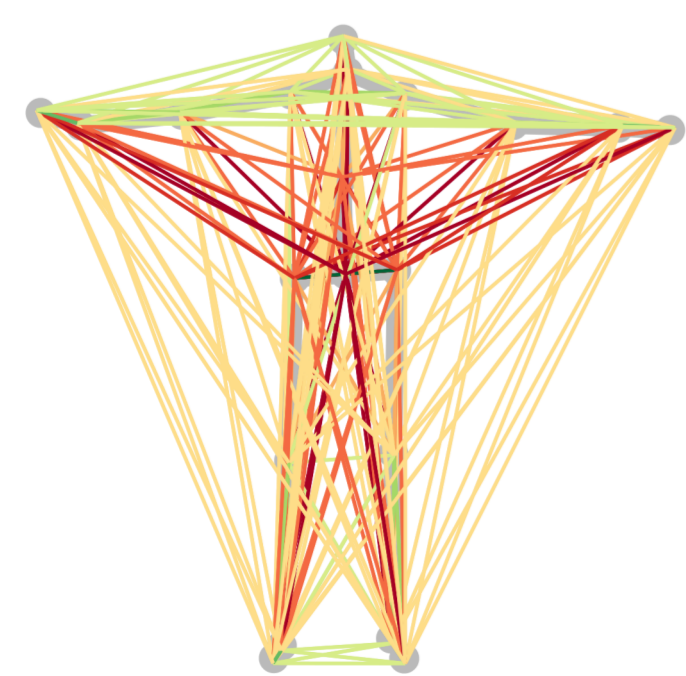
- Learning the graph structure:** Minimize KL-divergence between the high-dimensional pose distribution $q(\mathbf{X})$ and the tree-structured network $p(\mathbf{X}) = \prod_{j=1}^{|V|} p(X_j | X_{pa(j)})$,

$$\mathcal{G} := \operatorname{argmin}_{pa} \operatorname{KL}(q(\mathbf{X}) \parallel p(\mathbf{X})) = \operatorname{MST}(\mathcal{G}'),$$

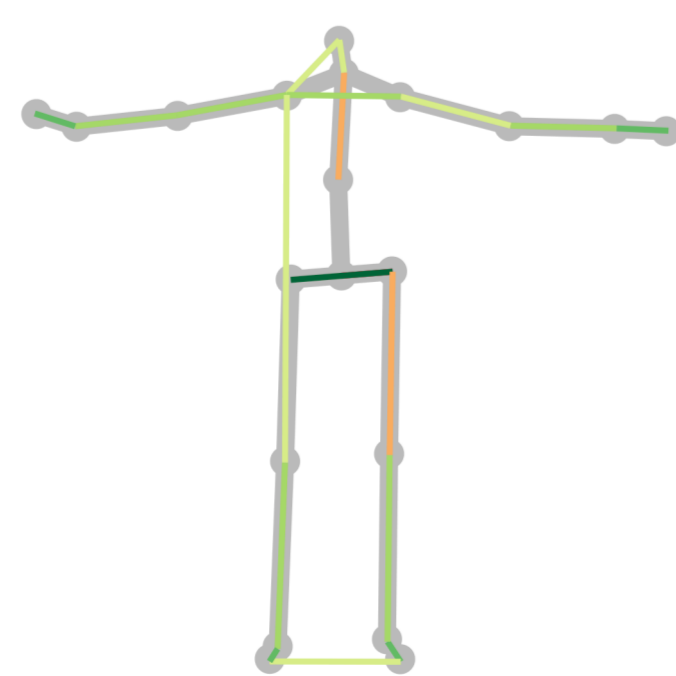
where \mathcal{G}' is the complete graph with edge weights $e_{jk} = \widehat{\operatorname{MI}}(X_j, X_k)$.



Kinematic chain



Mutual information



Chow-Liu tree

- Learning the conditional distributions:**

We use a conditional kernel density estimate (CKDE) to learn the local models of the inferred tree,

$$p(X_j | X_{pa(j)}) = \frac{p(X_j, X_{pa(j)})}{\int_{X_j} p(X_j, X_{pa(j)}) dX_j} = \frac{\sum_i \mathcal{N}((X_j, X_{pa(j)}) | (X_j^{(i)}, X_{pa(j)}^{(i)}), BB^T)}{\sum_i \mathcal{N}(X_{pa(j)} | X_{pa(j)}^{(i)}, (BB^T)|_{X_{pa(j)}})},$$

where $p(X_j, X_{pa(j)})$ is an unconditional KDE with isotropic Gaussian kernel and bandwidth B proportional to the square root of the covariance.

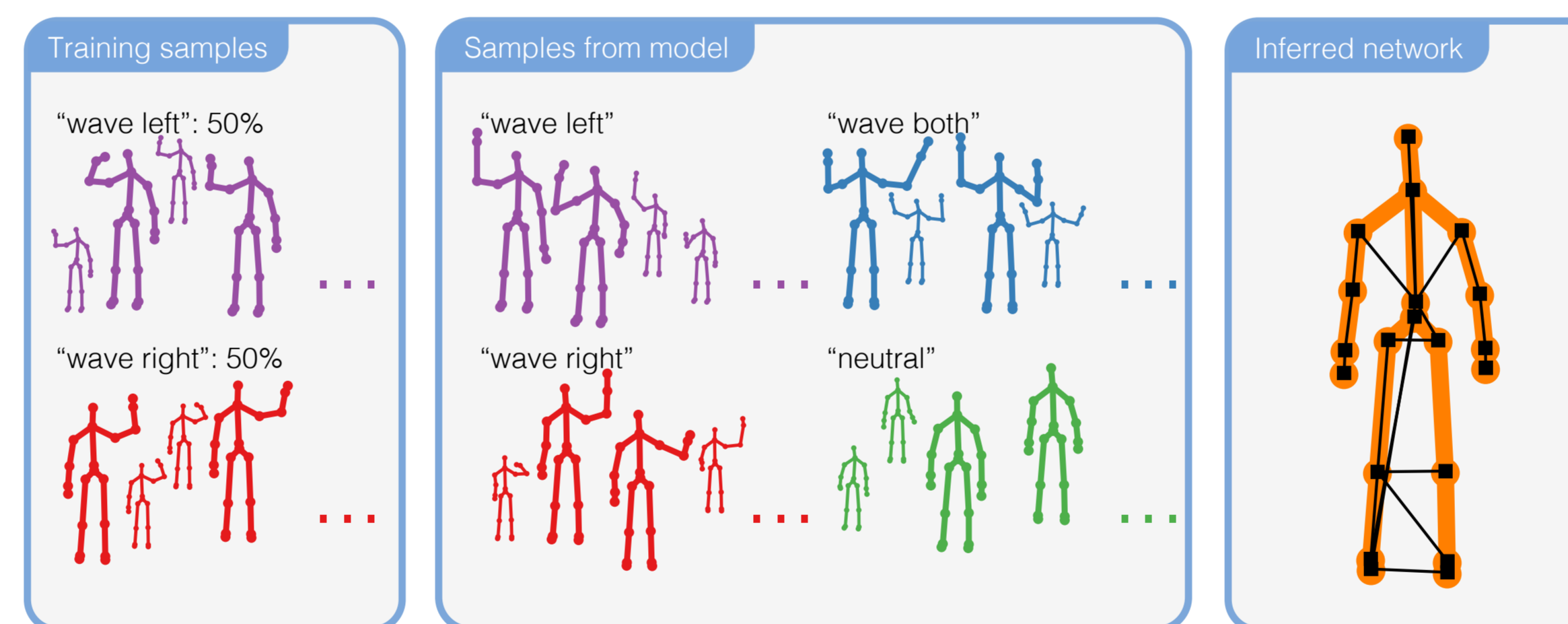
- Important operations are efficient:**

- Computation of a log-likelihood requires $\mathcal{O}(|V|)$ KDE evaluations.
- Ancestral sampling requires $\mathcal{O}(|V|)$ samples from the local models. [Gaussian mixture models with non-uniform weight distribution]

3 Compositionality & Generalization

- Our formulation allows to freely combine substructures, but only if they do not share a lot of information.

⇒ Compositionality exactly where needed and only where appropriate.



- We compute expected log-likelihoods for our Chow-Liu/CKDE model and several baselines on the Human 3.6M dataset.

Table 1: Expected log-likelihoods.

Method	Graph structure	Training	Testing
Gaussian	Global	-266.84	-271.15
KDE	Global	-239.61	-263.77
GPLVM*	Global	-327.85	-341.89
Gaussian linear network	Independent	-352.80	-345.94
	Kinematic chain (order 1)	-311.54	-310.98
	Kinematic chain (order 2)	-305.54	-307.88
CKDE network	Chow-Liu tree	-283.82	-284.03
	Independent	-322.64	-322.25
	Kinematic chain (order 1)	-260.04	-270.52
	Kinematic chain (order 2)	-247.35	-263.83
	Chow-Liu tree (ours)	-242.24	-254.98

*25% subsampling; FITC

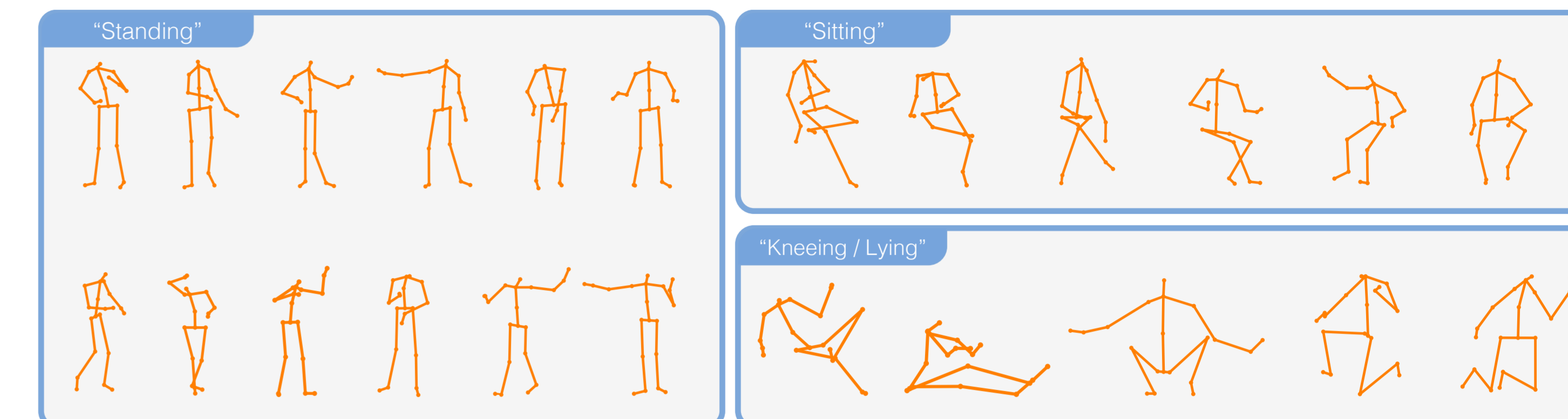


Figure 1: Samples drawn from a single Chow-Liu/CKDE model.

4 Live Scoring

- Applications in real-time environments require additional speed.
- Training:** Cluster the training points into clusters $\{C^{(i)}\}_i$ using k -means and build a kd -tree for their centres.
- Testing:** Given a test pose \mathbf{x} , use the kd -tree to compute a k -NN partitioning $\{C^{(i)}\}_i = C_e(\mathbf{x}) \uplus C_a(\mathbf{x})$ and approximate the likelihood as

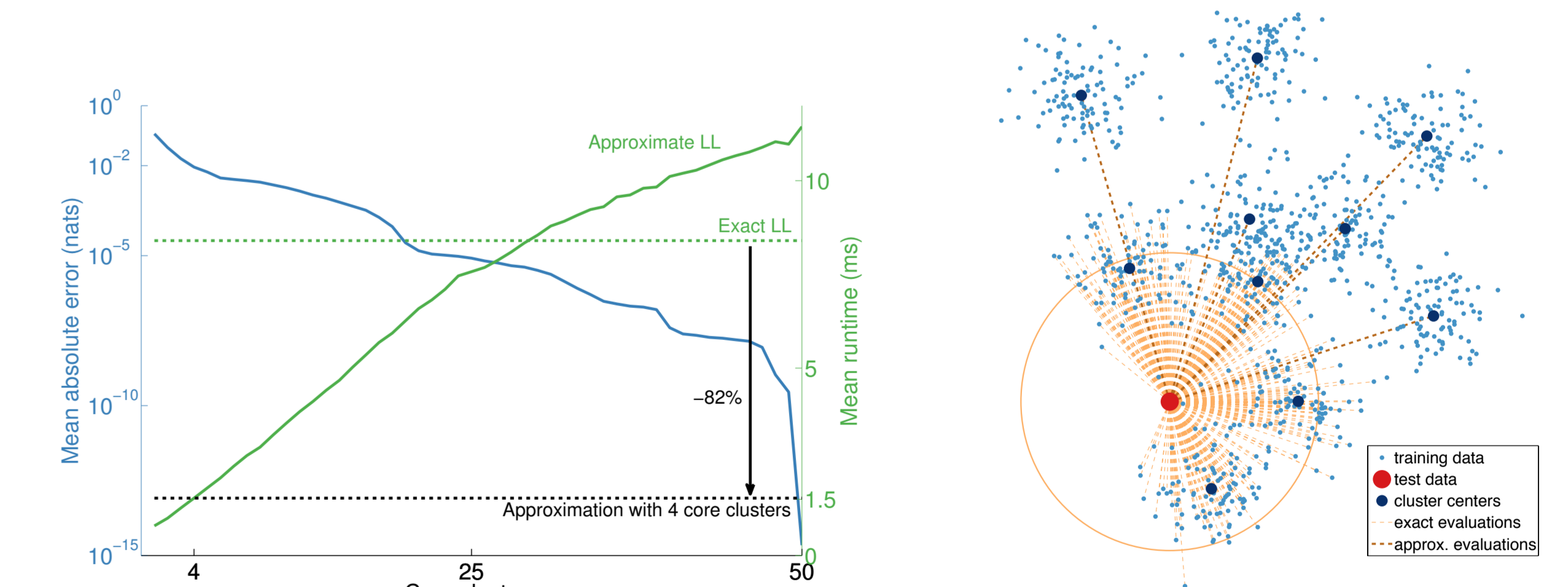
$$p(\mathbf{x}) \approx (S_e + S_a) / (N \cdot \det(B)),$$

with

$$S_e = \sum_{C \in C_e} \sum_{j \in C} \kappa(B^{-1}(\mathbf{x} - \mathbf{x}^{(j)})), \quad [\text{exact}]$$

$$S_a = \sum_{C \in C_a} |C| \kappa(B^{-1}(\mathbf{x} - \bar{C})), \quad [\text{approx.}]$$

where \bar{C} and $|C|$ denote the centre and size of cluster C , respectively.



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- [3] C. Ionescu, D. Papava, V. Olaru, and C. Sminchisescu. Human3.6M: Large Scale Datasets and Predictive Methods for 3D Human Sensing in Natural Environments. Technical report, University of Bonn, 2012.

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